

# AR 静止画プログラム例

```
import jp.nyatla.nyar4psg.*;  
  
MultiMarker ar;  
int id1;  
PImage img;  
  
void setup() {  
    size(1024, 768, P3D);  
    //img = loadImage("ar_photo0.png");  
    //img = loadImage("ar_photo1.png");  
    img = loadImage("ar_photo2.png");  
    ar = new MultiMarker(this, width, height, "camera_para.dat",  
NyAR4PsgConfig.CONFIG_PSG);  
    id1 = ar.addNyIdMarker(1, 60);  
}
```

```
void draw() {  
    ar.drawBackground(img);  
    ar.detect(img);  
  
    if (ar.isExist(id1)) {  
        ar.beginTransform(id1);  
        fill(120, 160, 240, 200);  
        translate(0, 0, 30);  
        box(60);  
        ar.endTransform();  
    }  
}
```

# AR 動画プログラム例

```
import jp.nyatla.nyar4psg.*;
import processing.video.*;

Movie movie;
MultiMarker ar;
int id1;

void setup() {
    size(640, 360, P3D);
    movie = new Movie(this, "marker_360p.mov");
    movie.loop();
    ar = new MultiMarker(this, width, height, "camera_para.dat",
NyAR4PsgConfig.CONFIG_PSG);
    id1 = ar.addNyIdMarker(1, 60);
}
```

```
void draw() {
    if (movie.available() == false) return;
    movie.read();
    ar.drawBackground(movie);
    ar.detect(movie);

    if (ar.isExist(id1)) {
        ar.beginTransform(id1);
        fill(120, 160, 240, 200);
        translate(0, 0, 30);
        box(60);
        ar.endTransform();
    }
}
```

# AR カメラ映像プログラム例

```
import processing.video.*;
import jp.nyatla.nyar4psg.*;

Capture cam;
MultiMarker ar;
int id1;

void setup() {
    size(640, 480, P3D);
    String[] cameras = Capture.list();
    println("Available cameras:");
    for (int i = 0; i < cameras.length; i++) {
        println(i, cameras[i]);
    }
    cam = new Capture(this, width, height, cameras[0]);
    //cam = new Capture(this, width, height, cameras[3]); // for Surface PC
    ar = new MultiMarker(this, width, height, "camera_para.dat",
NyAR4PsgConfig.CONFIG_PSG);
    id1 = ar.addNyIdMarker(1, 60);
    cam.start();
}
```

```
void draw() {
    if (cam.available() == false) return;
    cam.read();
    ar.drawBackground(cam);
    ar.detect(cam);

    if (ar.isExist(id1)) {
        ar.beginTransform(id1);
        fill(120, 160, 240, 200);
        translate(0, 0, 30);
        box(60);
        ar.endTransform();
    }
}
```